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Abstract #1661



English

SELF-REPLICATING MACHINES: FROM THEORY TO PRACTICE

We shall review theoretical work on self-replicating machines to determine any practical lessons that might be learned in translating from theory to practice. Theoretical work on self-replicating machines has strongly emphasised self-assembling systems assuming that complex parts are already available in the environment. Indeed, most practical work to date has similarly emphasised robotic assembly of pre-existing complex modules. For true self-replicating machines, this is insufficient and the entire supply chain from mining to extraction must be considered. Nevertheless, there are useful lessons to be learned from self-assembly models, particularly the central role played by robotic machines in the self-replication process. In theoretical models, they are abstracted as assembly manipulators but practical systems must include mining vehicles, physical and chemical processing plants, 3D printers, manufacturing tooling and assembly manipulators. The core components of these kinematic machines are motors and electronic controllers. Construction of such components from raw materials would constitute an existence proof for practical self-replicating machines.

French

No abstract title in French

No French resume

Author(s) and Co-Author(s)

Dr. Alex Ellery Associate professor Carleton University 4/26/2017 CIM | TPMS |

Profile of Dr. Alex Ellery



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Email(s):	aellery	/@mae.	.carleton.	ca
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Position:

Preferred Language: [Language not defined]

Addresses

Business	

Home

Biographies

Biography submitted with the abstract

Prof Ellery is a Canada Research Chair in Space Robotics & Space Technology at Carleton University. He has 170 publications including the authorship of two textbooks in the field of space robotics - An Introduction to Space Robotics (2000) and Planetary Rovers (2016). His interest in robotic in-situ resource utilisation stems from his conviction that the space environment will only open up for viable exploration and commercial exploitation once a robotic infrastructure is emplaced on the Moon, asteroids and Mars constructed from in-situ resources. The only means to achieve this at a reasonable cost will be through self-replicating machines.

Biography in the user profile

Collaborators

Author(s) and Presenter(s)

Author(s):

Dr. Alex Ellery

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Associate professor Carleton University	
Presenter(s):	
Dr. Alex Ellery Associate professor Carleton University	



Self-Replicating Machines: from Theory to Practice

Prof Alex Ellery

Space Exploration Engineering Group (SEEG)

Department of Mechanical & Aerospace Engineering

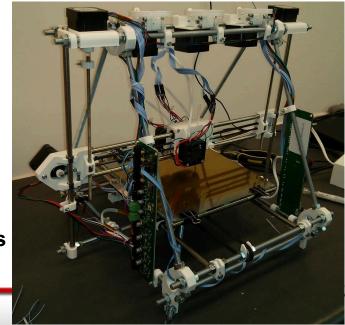
Carleton University

Planetary & Terrestrial Mining Sciences Symposium 2017, Montreal

Preamble

- We have previously presented the concept of a self-replicating machine on the Moon
- There are many variations on this theme
- My initial inspiration began with the RepRap FDM 3D printer - it can print some of its own plastic parts
- Full self-replication requires 3D printing:
 - (i) structural metal bars and components
 - (ii) electric motor drives
 - (iii) <u>electronics</u> boards
 - (iv) computer hardware/software
- Full self-replication also requires:
 - (i) self-assembly
 - (ii) self-power
 - (iii) material processing into feedstock (wire)
- From electric motors and electronics, all else follows







Kinematic Machines



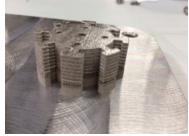
- 3D printers = XY printing head on Z deposition table = cartesian robot
- 3D printable motor system including actuators, control electronics and sensors:
 - (i) replace 3D printer head with 3 DOF wrist for parts assembly
 - (ii) construction of FabLab manufacturing tools lathe, milling station, drill press, bending press, etc
 - (iii) actuators for pumps and stirrers for unit chemical processes
 - (iv) beneficiation with crusher jaws
 - (v) centrifugal ball milling for surface finishing
 - (vi) vehicle mobility for mining with drilling/trenching/excavation mechanisms
 - (vii) serial **manipulators** with end-effectors model of von Neumann's Universal Constructor
- Any kinematic machine is a specific configuration of motors



Electric Motors



- We focus on the motor core of traditional DC electric motor
 - (a) **Plastic-coated wires** are **coiled** around grooved insulating **end-bobbins**
 - (b) Motor core constructed from alternating layers of silicon electrical steel (up to 3% Si) and insulating plastic/ceramic to minimise eddy currents but maximise magnetic threading
- SLM-printed motor core by Renishaw Canada
- Unfortunately, 316L steel!
- NRC Canada EBF3 to print Si steel motor core with kovar-based coils



- Submitted ESA bid to fund this activity adequately....
- Advantage high magnetic threading capability

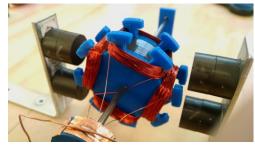


3D Printed Motor Core



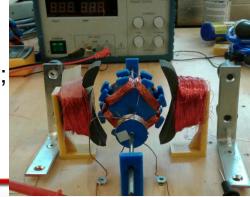
- Our motor core comprises Fe powder in a PLA matrix
- 50% Fe filings in PLA matrix by mass (ProtoPasta)





- 50% Fe filings in PLA by volume (NRC Can)
- We are building motors with Si steel powders in PLA to prevent detent
- ProtoPasta-based stator gives insufficient B-field
- Solution (a) ProtoPasta; (b) NRC;

(c) DIY







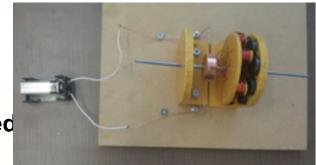
3D Printed Wire Coils



Pancake motor concept is an alternative motor

configuration

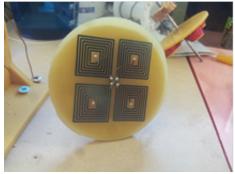
 We are exploring lithographically-printed wiring patterns



Single layer insufficient – multilayer design is underway

- Once motor core with wire coils have been printed, a complete 3D printed motor can be constructed
- Dual excitation motor uses core module for both rotor and stator poles
- This still requires manual assembly
- We shall explore design space of 3D printed motor designs using genetic algorithms



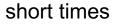




DIY 3D Metal Printers



- New "hobbyist" 3D printer to print in multiple materials including metals
- An integrated milling head will provide surface machining
- There are three power sources:
 - (a) **Propane burner** to heat a crucible
 - (b) **Induction melter** piped to an extruder printing head
 - (c) **Fresnel lens** to focus light onto a fibre optic bundle fed into printing head
- Al wire tracks printed onto silicone plastic insulation for

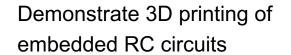












Higher Temperatures



- A lunar solar furnace-based foundry based on printed or cast Fresnel lens concentrators to create temperatures ~2700°C
- Regolith can be directly sintered into superior glass at 1300°C
- Anorthite CaAl₂Si₂O₈ for fibreglass
- Temperatures of 1600 are sufficient for steel alloys
- Print kovar wire onto pre-ceramic silicon plastic substrates
- Silicone plastic converted to silica ceramic by high temperature combustion in oxygen

$$SiO_xC_y + (1-x+2y)O_2 \rightarrow SiO_2 + yCO_2$$

- Silicone plastic 3D printed using FDM converted to ceramic with CO₂ recovery

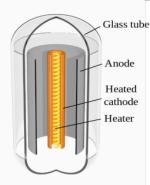
 steel printed onto silica substrate
- Multi-material 3D printing!



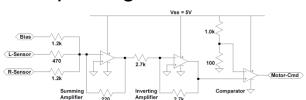
Neural Circuitry

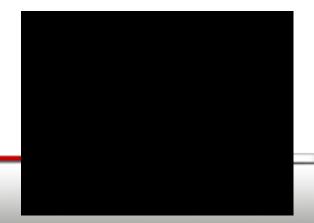


- Vacuum tubes are thermionic devices which use sintered tungsten resistance wire and Ni electrodes to heat cathode to ~1000°C in an evacuated glass envelope
- Problem: circuit complexity growth using von Neumann computational architecture



- We adopt Turing-complete recurrent neural nets composed of analogue neurons
- 3D printer acts as printing head of universal Turing machine printing neural net ccts (output) codified in iron core memory circuits (input
- Our modified Yamashida-Nakaruma neuron comprises weighted input, summing integrator and signum output
- Neural nets act as compressed programs with log footprint growth with task complexity







Vacuum Tubes



 First vacuum tube to be reverse engineered for 3D printing is magnetron – a macroscopic vacuum tube with "motor" elements



- Curious construction...
- Goal: 3D print solar power microsatellites....



Lunar Plenty



Ī	Functionality	Lunar Material
	Tensile structures	Wrought iron
	Compressive structures	Cast iron
	Elastic structures	Steel springs/flexures
		Silicone elastomers
	Thermal conductors	Fernico (eg. kovar)
	Thermal insulation	Glass (fibre)
		Ceramics such as TiO ₂
	Thermal tolerance	Tungsten
	Electrical conduction	Fernico (e.g. kovar) Nickel
	Electrical insulation	Glass
		Ceramic such as TiO ₂
		Silicone plastic
		Silicon steel
	Active electronics	Kovar
		Nickel
		Tungsten
		Glass
	Magnetic materials	Silicon steel
		Permalloy
	Sensors and sensory transduction	Quartz
		Selenium
	Optical structures	Polished nickel
		Glass
	Liquids	Silicone oils
		Water
	Gases	Oxygen
		Hydrogen



Lunar Volatiles



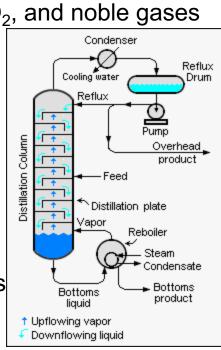
 RPM will demonstrate extraction of volatile from the lunar regolith, particularly water ice from lunar pole region

Solar wind has impregnated regolith with 96% hydrogen (~120 ppm), almost 4% He and trace amounts of H₂O, CO, CO₂, CH₄, N₂, NH₃, H₂S, SO₂, and noble gases

such as Ar

 Gases are preferentially adsorbed onto small particles of ilmenite

- Mining is simple scoop regolith into hopper
- Beneficiation may be achieved through motorised rock-jaw crushing and electrostatic/magnetic separation
- Heating regolith to 700°C releases 90% of volatiles
- Fractional distillation may be employed to separate gas fractions
- Reaction chambers require motorised pumps and valves to control flow





Carbon-Modest Silicone



- Plastic is restricted to flexible electrical insulator but we need to reduce C inventory imposed by hydrocarbon plastics
- Silicones (R₂SiO)_n, have O-Si-O backbones simplest is PDMS silicone oil
- Silicones are radiation-tolerant and temp resistant to 350°C (cf. 120°C)
- Syngas is converted to methanol over Al₂O₃ catalyst at 250°C and 5-10 MPa:
 CO + H₂ → CH₃OH
- Chloromethane by reacting methanol with HCl over Al₂O₃ catalyst at 350°C:
 CH₃OH + HCl → CH₃Cl + H₂O
- CH₃Cl is reacted with Si at 370 degrees with Cu (?) catalyst:
 2CH₃Cl + Si → (CH₃)₂SiCl₂
- This is hydrolysed to PDMS: n(CH₃)₂SiCl₂ + nH₂O → ((CH3)₂SiO)_n + 2nHCl
- HCl is recycled Cl must be imported from Earth
- Silicone oil may be used for hot isostatic pressing of metal powders



Iron Alloys for Motors

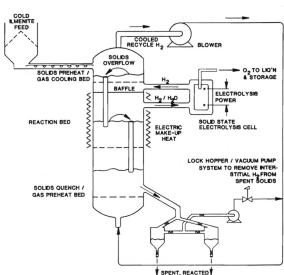


 RPM will demonstrate hydrogen reduction of ilmenite at ~1000°C to create oxygen, iron and rutile (proposed for RPM)

FeTiO₃ + H₂
$$\rightarrow$$
 Fe + TiO₂ + H₂O
2H₂O \rightarrow 2H₂ + O

- Hydrogen is recycled
- TiO₂ fibres for thermal insulation
- Wrought iron is tough but malleable
- Tool steel with <2% C + 9-18% W for cutting tools
- Silicon steel (up to 3% Si + >97% Fe) for motors
- Kovar is high electrical/thermal conductivity Fe alloy
 (53.5% Fe, 29% Ni, 17% Co, 0.3% Mn, 0.2% Si and <0.01% C) one of a family of Fernico alloys</p>
- Permalloy (80% Ni and 20% Fe) for magnetic shielding with μ_r~10⁵





Tunico (W-Ni-Co) Elements



- Mascons in impact craters indicate location of NiFe meteorite ores detectable as magnetic anomalies, eg. rim of South Pole Aitken crater
- Kamacite/taenite (NiFe alloys) is typically contaminated with Co
- Mond process at 40-80°C reacts impure Ni with CO and S catalyst which is reversed at 230°C/60 bar: Ni(CO)₄ ↔ Ni + 4CO
- S catalyst recovered at 750-1100°C from troilite (FeS) in meteoritic inclusions, lunar regolith (~1%), or lunar volatiles
- Co fraction of NiFe alloy adjusted by mixing recovered Fe and Ni metal
- Highland rock has ~0.3 μ g/g W but W is difficult to extract from wolframite (Fe,Mn(WO₄))
- Meteoritic NiFe alloys enriched in W microparticle inclusions which can be crushed and separated by froth flotation (W has high density of 19.3)



Power of Carbothermal Reduction



Carbothermal reduction of lunar anorthite (CaAl₂Si₂O₈)

$$4CH_4 \rightarrow 4C + 8H_2 (T=1400^{\circ}C)$$

$$CaAl_2Si_2O_8 + 4C \rightarrow CaO + Al_2O_3 + 2Si + 4CO (T=1650°C)$$

$$Al_2O_3 + 3H_2 \rightarrow 2Al + 3H_2O (T=1200-1300°C)$$

Carbothermal reduction of lunar olivine (Mg₂SiO₄):

$$Mg_2SiO_4 + 2CH_4 \rightarrow 2CO + 4H_2 + 2MgO + Si (T= 2000°C)$$

There are other relevant reactions to recycle and recover reagants

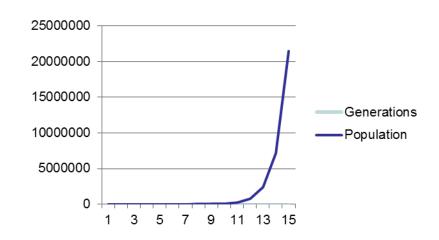
Self-Replication is Low-Cost!



Initial capital cost is amortised over an exponentially increasing productive capacity

$$P = \sum_{i=1}^{m} (1+r)^i$$

where r>1



- Specific cost drops exponentially because productive capacity grows faster than discount losses
- For r=2 over 13 generations, specific cost to the Moon has dropped from \$200,000/kg to ~\$1/kg
- Self-replication is the only means to develop low-cost access to space!

